# **Robot Operating Systems Essentials**



### **Expect these Contents**

Dive into the fascinating world of robotics, where you'll embark on a hands-on journey to build and control your very own delta robot. This course offers a comprehensive exploration of delta robot kinematics, assembly, and control mechanisms, including an introduction to the Robot Operating System (ROS), a crucial tool in modern robotics. From the fundamentals of robot construction to advanced control using both Arduino and ROS, you'll learn through practical, project-based sessions that culminate in a live demonstration of your robot.

- Understand delta robot kinematics and control principles
- Learn the delta robot building process, including material and component selection
- Program the delta robot using Arduino for task execution
- Debug and optimize robot performance for complex task execution

#### Summer School

- June 22 July 5, 2025 (2 weeks)
- € 2,750 €

🕞 On-campus

- **8** Supporting Program
- RWTH Certificate with 3 ECTS (approx. 75 hours)
- 🕅 Accommodation included

### Turn the theory into your own fully functional robot!

Gain new insights into robot design and control. You will build your own Delta Robot, which you can even take home with you at the end! Learn first-hand from industry experts and expand your own network!







## Robot Operating Systems Essentials -Summer School\*

TIME (CEST)	Sunday	Monday	Tuesday	Wednesday	Thursday	Friday	Saturday
08:00 - 08:30							
08:30 - 09:00							
09:00 - 09:30							
09:30 - 10:00			to the devidence		Introduction		
10:00 - 10:30		Pick up	Introduction & Basics of Kinematics of Delta Robots		to Delta Building Process & FastX Sup- port	Delta Assembly & Arduino Support	
10:30 - 11:00		Welcome Orientation					
11:00 - 11:30							
11:30 - 12:00							
12:00 - 12:30							
12:30 - 13:00		Lunch Break		City Trip	Lunch Break		
13:00 - 13:30							
13:30 - 14:00	\$	Get to know Aachen City Rally	Introduction & Basics of Kinematics of Delta Robots Visit of Insitute (IGMR)		Introduction to	Delta Assembly & Arduino Support	Free time for excursions, sight-seeing and self-study
14:00 - 14:30	Individual arrival				Delta Building Process &		
14:30 - 15:00					FastX Support		
15:00 - 15:30							
15:30 - 16:00							
16:00 - 16:30							
16:30 - 17:00							
17:00 - 17:30							
17:30 - 18:00							
18:00 - 18:30							
18:30 - 19:00							
19:00 - 19:30							
19:30 - 20:00							
20:00 - 20:30							
20:30 - 21:00							



Organizational and social event Lecture, academic program

Academic supporting program (institute/company visit, scheduled self-study, group work, case study, project work)

\*Exemplary Schedule (Information presented is subject to change. Errors and omissions reserved)







## Robot Operating Systems Essentials -Summer School\*

TIME (CEST)	Sunday	Monday	Tuesday	Wednesday	Thursday	Friday	Saturday		
08:00 - 08:30									
08:30 - 09:00									
09:00 - 09:30		Delta Kinematics on Arduino	Introduction to ROS (Short Ver- sion: msgs, topics, pub, sub, nodes, launch, rviz)	Program a ROS Node to send Poses to Arduino	Implementa- tion and Demonstra- tion	Demonstrati- on in front of Professors			
09:30 - 10:00									
10:00 - 10:30									
10:30 - 11:00									
11:00 - 11:30									
11:30 - 12:00									
12:00 - 12:30									
12:30 - 13:00				Lunch Break					
13:00 - 13:30									
13:30 - 14:00	Free time for excursions,	Test: Complex Path Execution	On FastX	Bring the Kinematics Calculation to a ROS Node (FastX)	Preparation for final exam		S		
14:00 - 14:30						Farewell	Individual		
14:30 - 15:00	sightseeing and					Event	departure		
15:00 - 15:30	self-study								
15:30 - 16:00									
16:00 - 16:30									
16:30 - 17:00									
17:00 - 17:30									
17:30 - 18:00									
18:00 - 18:30									
18:30 - 19:00									
19:00 - 19:30									
19:30 - 20:00				Barbeque					
20:00 - 20:30									
20:30 - 21:00									

Organizational and social event

Lecture, academic program

Academic supporting program (institute/company visit, scheduled self-study, group work, case study, project work)

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